

ROTATION REVIEW

1. a. $\omega = 4 \text{ rad/s}$

$$4 \frac{\text{RAD}}{\text{s}} \left| \frac{1 \text{ REV}}{2\pi \text{ RAD}} \right| = \boxed{0.64 \frac{\text{REV}}{\text{s}}}$$

b. $v = r\omega$

$$v = 0.4 \text{ m} (4 \text{ RAD/s})$$

$$\boxed{v = 1.6 \text{ m/s}}$$

c. $\omega_0 = 4 \text{ rad/s}$

$$\omega = 12 \text{ rad/s}$$

$$\alpha = 2 \text{ rad/s}^2$$

$$\theta = ?$$

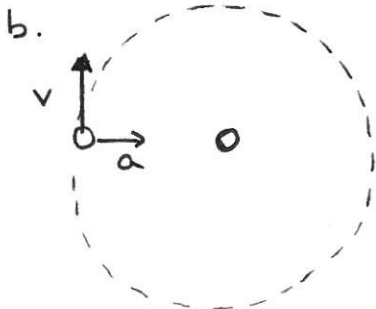
$$\omega^2 = \omega_0^2 + 2\alpha\theta$$

$$\frac{\omega^2 - \omega_0^2}{2\alpha} = \theta$$

$$\frac{12^2 - 4^2}{2(2)} = \theta$$

$$\boxed{32 \text{ RAD} = \theta}$$

2. a. A REVOLUTION IS THE MOVEMENT OF ONE OBJECT AROUND ANOTHER. A FORCE (TENSION, FRICTION, OR GRAVITY FOR EXAMPLE) MUST ACT TO KEEP THE OBJECT ON A CIRCULAR PATH.



c. A ROTATION IS THE MOVEMENT OF AN OBJECT AROUND ITS OWN AXIS. A TORQUE IS NEEDED TO SPIN AN OBJECT ON ITS AXIS.

d. $v = r\omega$ $a = r\alpha$ $x = r\theta$

e. MASS AND THE LOCATION OF THE MASS IN RELATION TO THE PIVOT POINT.

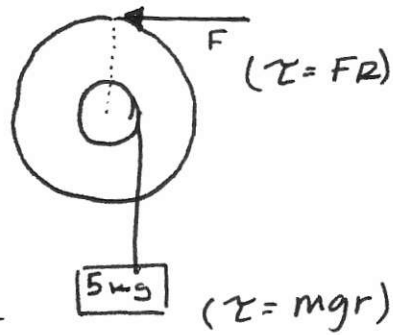
3. a. $\Sigma \tau = I\alpha = FR - mgr$

EQUILIBRIUM $\rightarrow 0 = FR - mgr$

$mgr = FR$

$5\text{kg}(10\text{m/s}^2)(.2\text{m}) = F(0.8\text{m})$

$12.5\text{N} = F$



b. $\Sigma \tau = I\alpha = Tr$ $\Sigma F = ma = mg - T$

$I \frac{a}{r} = Tr$ $ma = mg - T$

$5a = 50 - T$

$\frac{I}{r^2} a = T$

$\frac{8}{.2^2} a = T$

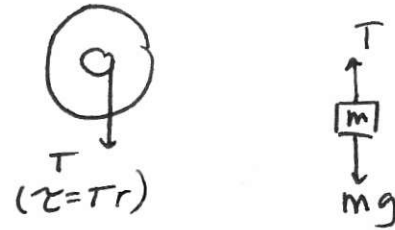
$200a = T$

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$5a = 50 - T$

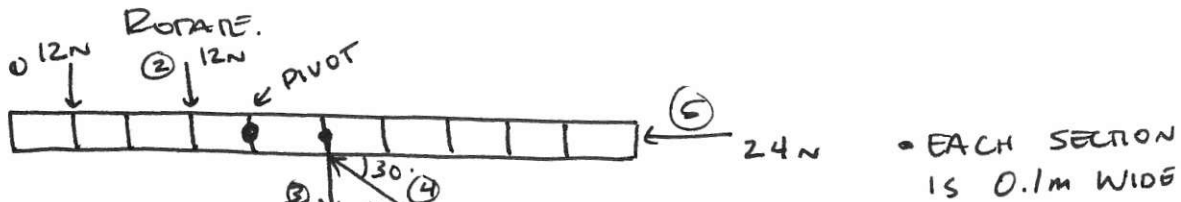
$205a = 50$

$a = 0.244\text{m/s}^2$



c. MOVING MORE MASS TO THE OUTER EDGE OF THE WHEEL INCREASES THE MOMENT OF INERTIA. A BIGGER I DECREASES THE ACCELERATION OF THE SYSTEM BECAUSE THE SYSTEM IS MORE DIFFICULT TO

3.3.



THE WEIGHT ACTS AT THE CENTER

a. $\Sigma \tau = 3.6 + 1.2 - 2 - F(.5)(.1)$

$\Sigma \tau = 0$ (EQUILIBRIUM)

$3.6 + 1.2 - 2 - F(.05) = 0$

$2.8 = F(.05)$

$56\text{N} = F$

TORQUES

① $\tau = 12\text{N}(.3\text{m}) = 3.6\text{N}\cdot\text{m}$ CCW +

② $\tau = 12\text{N}(.1\text{m}) = 1.2\text{N}\cdot\text{m}$ CCW +

③ $\tau = mg(.1\text{m}) = 2\text{N}\cdot\text{m}$ CW -

④ $\tau = F \sin 30^\circ (.1\text{m}) = F(.5)(.1)$ CW -

⑤ $\tau = 0$

b. $\Sigma \tau = 3.6 + 1.2 - 2$

$I\alpha = 2.8$

$\alpha = \frac{2.8}{0.4} = 7\text{RAD/s}^2$

4. a. $MR^2 = 1.92 \text{ kg m}^2$

$$M = \frac{1.92}{(1.8)^2}$$

$$M = 3 \text{ kg}$$

b. $\Sigma \tau = I \alpha$

$$FR = I \alpha$$

$$28.8(1.8) = (1.92) \alpha$$

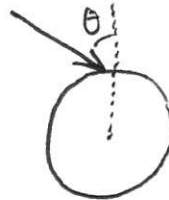
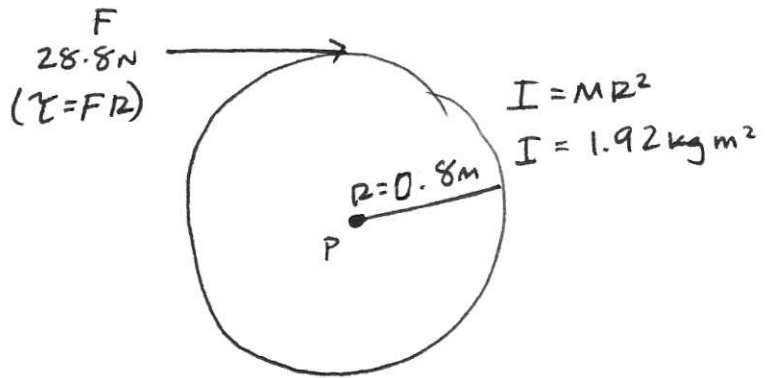
$$12 \text{ rad/s}^2 = \alpha$$

c. 1. DECREASE F

2. APPLY F AT AN ANGLE \implies

3. INCREASE MASS

4. INCREASE RADIUS OF WHEEL



5. $\omega_0 = 4 \text{ rad/s}$

$$\omega = 0$$

$$t = 2 \text{ s}$$

$$\alpha = ?$$

$$\omega = \omega_0 + \alpha t$$

$$\frac{\omega - \omega_0}{t} = \alpha$$

$$\frac{0 - 4}{2} = \alpha$$

$$-2 \text{ rad/s}^2 = \alpha$$

$$\tau = I \alpha$$

$$\tau = I \alpha$$

$$\tau = 500 \text{ kg m}^2 (2 \text{ rad/s}^2)$$

$$\tau = 1000 \frac{\text{kg m}^2}{\text{s}^2}$$

6. a. YES. NOTHING FROM OUTSIDE OF THE MAN/WEIGHT/ PLATFORM/EARTH SYSTEM ACTS ON THE OBJECTS.

- ANGULAR MOMENTUM WILL BE CONSERVED BECAUSE THERE ARE NO OUTSIDE TORQUES.

b. THE MAN WILL SPEED UP \rightarrow HE DECREASES HIS MOMENT OF INERTIA & INCREASES HIS ANGULAR VELOCITY.

(BY PULLING HIS ARMS IN HE DOES + WORK ON THE SYSTEM).

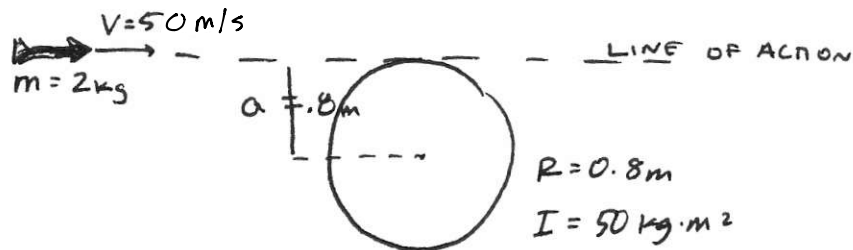
c. $L_i = L_f$

$$I_i \omega_i = I_f \omega_f$$

$$500 \left(\frac{6}{\pi} \right) = I_f \left(\frac{8}{\pi} \right)$$

$$375 \text{ kg m}^2 = I_f$$

7.



$$L_i = L_f$$

$$L_D + L_W = L_D + W$$

$$mva + 0 = (I_D + I_W) \omega$$

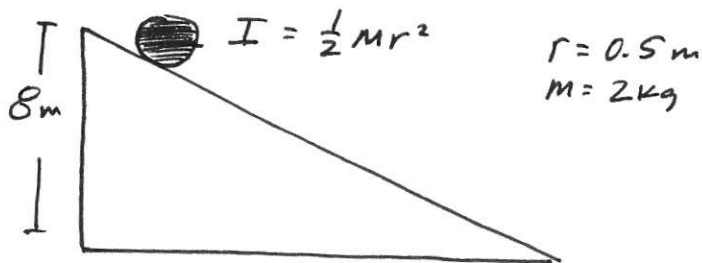
$$mv a = (mR^2 + I) \omega$$

$$2(50)(0.8) = (2(0.8)^2 + 50) \omega$$

$$80 = (51.28) \omega$$

$$\boxed{1.6 \text{ rad/s} = \omega}$$

8.



a. $E_{\text{TOP}} = mgh$

$E_{\text{BOTTOM}} = K + K_{\text{ROT}} \Rightarrow$ BECAUSE THE OBJECT ROLLS W/OUT SLIPPING IT WILL HAVE BOTH FORMS OF KINETIC ENERGY

$$E_{\text{TOP}} = E_{\text{BOTTOM}}$$

$$mgh = \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2 \quad \left[I = \frac{1}{2} m r^2, \omega = \frac{v}{r} \right]$$

$$mgh = \frac{1}{2} m v^2 + \frac{1}{2} \left(\frac{1}{2} m r^2 \right) \left(\frac{v^2}{r^2} \right)$$

$$mgh = \frac{1}{2} m v^2 + \frac{1}{4} m v^2$$

$$mgh = \frac{3}{4} m v^2$$

$$10(8) = \frac{3}{4} v^2$$

$$\boxed{10.3 \text{ m/s} = v}$$

$$\rightarrow \omega = \frac{v}{r} = \frac{10.3}{0.5 \text{ m}}$$

$$\boxed{\omega = 20.6 \text{ rad/s}}$$

8. b. WITHOUT FRICTION, THE DISK WILL NOT BEGIN TO ROLL

$$E_T = U_g \quad (\leftarrow \text{No } v, \text{ No } \omega)$$

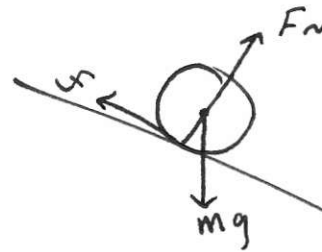
$$E_B = K \quad (\text{No } \omega)$$

$$mgh = \frac{1}{2}mv^2$$

$$2gh = v^2$$

$$\boxed{12.7 \text{ m/s} = v}$$

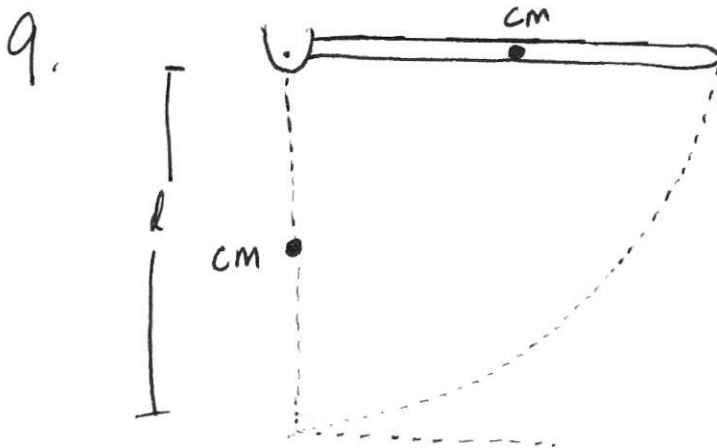
↑
 $v_b > v_a$ BECAUSE ALL OF THE POTENTIAL ENERGY BECAME KINETIC & NONE BECAME ROTATIONAL KINETIC.



• THE ONLY TORQUE IS FRICTION
 - WITHOUT FRICTION, $\sum \tau = 0 \Rightarrow$ IT NEVER SPINS.

$$\boxed{\omega = 0}$$

C. THE HOOP HAS A GREATER ROTATIONAL INERTIA THAN THE DISK \rightarrow MORE ENERGY WILL BE ROTATIONAL KE AND LESS WILL BE KINETIC (BECAUSE THE HOOP IS HARDER TO SPIN). THE HOOP WILL HAVE A SMALLER VELOCITY AND A SMALLER ANGULAR VELOCITY.



a. $U_g = mgl/2 \leftarrow$ THE POTENTIAL ENERGY IS MEASURED FROM THE C.M.
 $= 3(10)(1.2)/2$
 $\boxed{U_g = 18 \text{ J}}$

b. THE ROD WILL HAVE ROTATIONAL KE AT THE BOTTOM BECAUSE IT IS SPINNING ABOUT A POINT

c. $E_{\text{HORIZ}} = E_{\text{VERT}}$
 $mgl/2 = \frac{1}{2}I\omega^2$
 $18 \text{ J} = \frac{1}{2}(\frac{1}{3}m l^2)\omega^2$
 $18 \text{ J} = \frac{1}{2}(\frac{1}{3}(3 \text{ kg})(1.2 \text{ m})^2)\omega^2$
 $\boxed{5 \text{ rad/s} = \omega}$

d. $v = r\omega$
 $v = 1.2 \text{ m}(5 \text{ rad/s})$
 $\boxed{v = 6 \text{ m/s}}$